

# Lie algebras: basics, nilpotency and solvability

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## Definition

A *Lie algebra* is a vector space  $L$  over  $K = \bar{K}$  ( $\text{char}(K) = 0$ ) endowed with a bilinear operation

$$[\cdot, \cdot] : L \times L \longrightarrow L$$

that satisfies the following properties:

- 1  $[x, x] = 0$  for every  $x \in L$ .
- 2  $[x, [y, z]] + [z, [x, y]] + [y, [z, x]] = 0$  for every  $x, y, z \in L$ .

## Example

Any associative algebra  $(A, +, \cdot)$  is a Lie algebra when defining  $[x, y] := xy - yx$  for every  $x, y \in A$ .

# The tangent space at the identity

## Definition

Let  $\mathbb{G}$  be a linear algebraic group. The set of *derivations* supported on the  $K$ -algebra  $K[\mathbb{G}]$  is

$$\text{Der}(K[\mathbb{G}]) := \{\tilde{\delta} \in \text{End}_K(K[\mathbb{G}]) : \tilde{\delta}(fg) = \tilde{\delta}(f)g + f\tilde{\delta}(g) \quad \forall f, g \in K[\mathbb{G}]\}.$$

## Lemma

If  $\tilde{\delta}, \tilde{\eta} \in \text{Der}(K[\mathbb{G}])$ , then  $[\tilde{\delta}, \tilde{\eta}] := \tilde{\delta}\tilde{\eta} - \tilde{\eta}\tilde{\delta} \in \text{Der}(K[\mathbb{G}])$ . Moreover, we have that  $[\cdot, \cdot]$  is bilinear and

- (a)  $[\tilde{\delta}, \tilde{\delta}] = 0$  for every  $\tilde{\delta} \in \text{Der}(K[\mathbb{G}])$ .
- (b)  $[\tilde{\delta}, [\tilde{\eta}, \tilde{\theta}]] + [\tilde{\eta}, [\tilde{\theta}, \tilde{\delta}]] + [\tilde{\theta}, [\tilde{\delta}, \tilde{\eta}]] = 0$  for every  $\tilde{\delta}, \tilde{\eta}, \tilde{\theta} \in \text{Der}(K[\mathbb{G}])$ .

In other words,  $(\text{Der}(K[\mathbb{G}]), [\cdot, \cdot])$  is a Lie algebra.

# The tangent space at the identity

## Definition

Let  $x \in \mathbb{G}$ . Consider  $\lambda_x : K[\mathbb{G}] \rightarrow K[\mathbb{G}]$  the algebra map defined as  $(\lambda_x(f))(h) := f(x^{-1}h)$  for every  $f \in K[\mathbb{G}]$  and  $h \in \mathbb{G}$ . Then the set of *left invariant  $\mathbb{G}$ -derivations* is

$$\text{Der}_{\mathbb{G}}(K[\mathbb{G}]) := \{\tilde{\delta} \in \text{Der}(K[\mathbb{G}]) : \tilde{\delta}\lambda_x = \lambda_x\tilde{\delta} \text{ for every } x \in \mathbb{G}\}.$$

$\text{Der}_{\mathbb{G}}(K[\mathbb{G}])$  is closed under  $[\cdot, \cdot]$ , and so it is a Lie algebra, often called  $\text{Lie}(\mathbb{G})$ .

## Theorem

*We have a 1:1 correspondence between the elements of  $\text{Lie}(\mathbb{G})$  and the elements of the tangent space to  $\mathbb{G}$  at the identity, namely*

$$T_1(\mathbb{G}) := \{\delta \in \text{Hom}(K[\mathbb{G}], K) : \delta(fg) = (\delta f)g(1) + f(1)(\delta g) \quad \forall f, g \in K[\mathbb{G}]\}.$$

# The tangent space at the identity

- The tangent space to  $\mathbb{G}$  at the identity is naturally a Lie algebra.
- $\text{Lie}(\text{GL}_n(K)) \cong \mathfrak{gl}_n(K)$  as Lie algebras, where  $\mathfrak{gl}_n(K)$  is the vector space of the  $n \times n$   $K$ -matrices endowed with the structure of a Lie algebra using the commutator operation.
- $\text{Lie}(\text{SL}_n(K)) \cong \mathfrak{sl}_n(K)$  as Lie algebras, where  $\mathfrak{sl}_n(K)$  is the vector space of the  $n \times n$   $K$ -matrices with zero trace, endowed with the structure of a Lie algebra using the commutator operation.

From now on,  $L$  will denote a finitely dimensional Lie algebra over  $K$ .

## Definition

If  $E$  a subspace of  $L$  such that  $[E, E] \subseteq E$ . Then  $E$  is called a *subalgebra* of  $L$ . If, moreover,  $[E, L] \subseteq E$ , then  $E$  is called an *ideal* of  $L$ .

## Definition

Let  $L$  and  $M$  be two Lie algebras. A vector spaces morphism  $\phi : L \rightarrow M$  is called a *Lie algebra map* if  $[\phi(x), \phi(y)] = \phi([x, y])$  for every  $x, y \in L$ .

- One can define quotients and prove the usual isomorphism theorems.

## Definition

A *representation* of  $L$  is a Lie algebra map  $L \rightarrow \mathfrak{gl}_n(K)$  for some  $n \in \mathbb{N}$ .

# The adjoint representation

## Definition

The *adjoint representation* of  $L$  is the representation

$$\begin{aligned}\mathrm{ad}_L : L &\longrightarrow \mathfrak{gl}(L) \\ x &\longmapsto [x, \cdot],\end{aligned}$$

where  $\mathfrak{gl}(L)$  is the group of  $K$ -endomorphisms of  $L$  as a vector space, endowed with the structure of a Lie algebra by using the commutator.

## Definition

The *center* of  $L$  is  $\zeta(L) := \ker(\mathrm{ad}_L)$ . If  $\zeta(L) = L$ , we say that  $L$  is *abelian*.

## Lemma

$\mathrm{Im}(\mathrm{ad}_L) \subseteq \mathrm{Der}(L)$  and we have an injection

$$L/\zeta(L) \longrightarrow \mathrm{Der}(L) \subseteq \mathfrak{gl}(L).$$

- We call  $\mathfrak{n}_n(K)$  the set of strictly upper triangular  $n \times n$  matrices. It is a subalgebra of  $\mathfrak{gl}_n(K)$ .
- We call  $\mathfrak{b}_n(K)$  the set of upper triangular  $n \times n$  matrices. It is a subalgebra of  $\mathfrak{gl}_n(K)$ . Also,  $\mathfrak{n}_n(K)$  is an ideal inside  $\mathfrak{b}_n(K)$  and we have  $[\mathfrak{b}_n(K), \mathfrak{b}_n(K)] = \mathfrak{n}_n(K)$ .
- The set of all diagonal matrices is an abelian subalgebra of  $\mathfrak{gl}_n(K)$ .
- The center of  $\mathfrak{gl}_n(K)$  is the Lie algebra of scalar matrices.

## Definition

Let  $L$  be a Lie algebra and consider the sequence

$$L^1 := [L, L], \quad L^j := [L, L^{j-1}] \quad \text{for } j > 1.$$

$L$  is called *nilpotent* if  $L^j = 0$  for some  $j > 0$ .

- 1 Abelian Lie algebras are nilpotent.
- 2 The subalgebra  $\mathfrak{n}_n$  of  $\mathfrak{sl}_n(K)$  consisting of strictly upper triangular matrices is nilpotent.

$$\begin{pmatrix} 0 & * & \dots & * \\ \vdots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & * \\ 0 & \dots & \dots & 0 \end{pmatrix} \begin{pmatrix} 0 & * & \dots & * \\ \vdots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & * \\ 0 & \dots & \dots & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & * & \dots & * \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & * \\ \vdots & \ddots & \ddots & \ddots & 0 \\ 0 & \dots & \dots & \dots & 0 \end{pmatrix}$$

## Proposition

Let  $L$  be a Lie algebra.

- (a) If  $L$  is nilpotent, then its subalgebras and homomorphic images are so.
- (b) If  $L/\zeta(L)$  is nilpotent, then  $L$  is nilpotent.
- (c) If  $L$  is nilpotent, then  $\zeta(L) \neq 0$ .

## Proof

- (a) If  $E$  is a subalgebra of  $L$ , then  $E^j \subseteq L^j$ . If  $f : L \rightarrow M$  is an algebra map, then  $f(L^j) = f(L)^j$ .
- (b) If  $L/\zeta(L)$  is nilpotent, then  $(L/\zeta(L))^j = L^j/(\zeta(L) \cap L^j) = 0$  for some  $j$ . This means that  $L^j \subseteq \zeta(L)$ , therefore  $L^{j+1} \subseteq [L, \zeta(L)] = 0$ .
- (c) Consider  $j$  minimal such that  $L^j = 0$ . Then  $L^{j-1} \neq 0$  and the condition  $0 = L^j = [L, L^{j-1}]$  implies that  $L^{j-1} \subseteq \zeta(L)$ .

## Definition

Let  $x \in L$ . Then  $x$  is *ad-nilpotent in  $L$*  if  $\text{ad}_L(x)$  is a nilpotent element of  $\mathfrak{gl}(L)$ , i.e. if there exists a  $m \in \mathbb{N}$  such that  $(\text{ad}_L(x))^m \equiv 0$ .

## Lemma

*If  $L$  is nilpotent, then any element of  $L$  is  $\text{ad}_L$ -nilpotent.*

## Proof

$L^j = 0$  implies that  $(\text{ad}_L(x))^j(y) = [x, [x, \dots, [x, y]]] = 0$  for every  $x, y \in L$ .

## Lemma

Let  $x \in \mathfrak{gl}(V)$  for some vector space  $V$ . If  $x$  is a nilpotent endomorphism, then  $x$  is ad-nilpotent in  $\mathfrak{gl}(V)$ .

## Proof

Let  $x \in \mathfrak{gl}(V)$  be a nilpotent endomorphism. Define

$$\begin{aligned} \lambda_x : \text{End}_K(V) &\longrightarrow \text{End}_K(V) & \rho_x : \text{End}_K(V) &\longrightarrow \text{End}_K(V) \\ y &\longmapsto x \circ y & y &\longmapsto y \circ x \end{aligned}$$

$\lambda_x, \rho_x \in \text{End}_K(\text{End}_K(V))$ , they commute and they are nilpotent. Hence we have that  $\text{ad}_{\mathfrak{gl}(V)}(x) = \lambda_x - \rho_x$  is nilpotent.

## Theorem

*Let  $L \subseteq \mathfrak{gl}(V)$  be a Lie algebra. If  $V \neq 0$  and  $L$  consists of nilpotent endomorphisms, then there exists  $v \in V$ ,  $v \neq 0$ , such that  $Lv = 0$ .*

**Proof** Use induction on  $\dim L$ .

- If  $\dim L = 1$ , then  $L = Kx$  for some  $x \in L$ . Take  $v \in \ker(x)$ .
- Assume now that the statement holds for every  $L'$  subalgebra of  $\mathfrak{gl}(V)$  with  $\dim L' < \dim L$ .
- A subalgebra  $M \subset L$  acts on  $L/M$  via the adjoint representation.
- By inductive hypothesis, there exists a vector  $x + M \in L/M$ ,  $x \notin M$ , killed by the image of  $M$  in  $\mathfrak{gl}(L/M)$ .
- The normalizer  $N_L(M) := \{y \in L : [y, z] \in M \text{ for every } z \in M\}$  properly contains  $M$ .

## Proof

- Let  $M$  be a maximal proper subalgebra of  $L$ . Then  $N_L(M) = L$ , i.e.  $M$  is an ideal.
- $M$  has codimension one in  $L$ , so  $L = M + Kz$  for any  $z \in L \setminus M$ .
- By induction,  $W := \{v \in V : Mv = 0\}$  is nonzero.
- For every  $x \in L$ ,  $y \in M$ ,  $w \in W$  we have  $yx(w) = xy(w) - [x, y]w = 0$ , i.e.  $W$  is stable under the action of  $L$ .
- Let  $z \in L \setminus M$  act on  $W$  and choose  $0 \neq v \in W$  such that  $zv = 0$ . Then  $Lv = 0$ .

## Theorem (Engel)

*The Lie algebra  $L$  is nilpotent if and only if every element of  $L$  is  $\text{ad}_L$ -nilpotent.*

### Proof

- Let  $L$  be composed of  $\text{ad}$ -nilpotent elements, and use induction on  $\dim L$ .
- If  $\dim L = 1$ , then  $L$  is abelian.
- Work with  $\text{ad}_L(L) \subseteq \mathfrak{gl}(L)$ . The previous theorem allows us to find a nonzero  $x \in L$  such that  $[x, L] = 0$ .
- $L/\zeta(L)$  has smaller dimension than  $L$ . By inductive hypothesis,  $L/\zeta(L)$  is nilpotent.
- $L$  is nilpotent.

## Definition

Let  $V$  be a vector space of dimension  $n \in \mathbb{N}$ . A *flag* on  $V$  is a collection of subspaces  $0 \subset V_1 \subset \cdots \subset V_n = V$  such that  $\dim V_i = i$ .

## Corollary

*If  $L \subseteq \mathfrak{gl}(V)$  is a Lie algebra consisting of nilpotent elements, then there exists a flag  $0 \subset V_1 \subset \cdots \subset V_n = V$  such that  $xV_i \subseteq V_{i-1}$  for every  $x \in L$ ,  $i = 1, \dots, n$ .*

## Proof

- Take a vector  $v_1 \in V$  such that  $Lv_1 = 0$ , and define  $V_1 := Kv_1$ .
- Work on  $V/V_1$ : there exists a vector  $v_2 \in V \setminus V_1$  such that  $Lv_2 \subseteq V_1$ .
- Define  $V_2 := Kv_1 + Kv_2$  and proceed inductively.

## CONCLUSIONS

- Any Lie algebra  $L \subseteq \mathfrak{gl}(V)$  consisting of nilpotent elements can be seen as a subalgebra of the algebra  $\mathfrak{n}$  of strictly upper triangular matrices.
- A Lie algebra  $L$  is nilpotent if and only if  $\text{ad}_L(L) \subseteq \mathfrak{gl}(L)$  consists of nilpotent elements, and so it can be seen as a subalgebra of the algebra  $\mathfrak{n}$ .

## Definition

Let  $L$  be a Lie algebra and consider the sequence

$$L^{(1)} := [L, L], \quad L^{(j)} := [L^{(j-1)}, L^{(j-1)}] \quad \text{for } j > 1.$$

$L$  is called *solvable* if  $L^{(j)} = 0$  for some  $j > 0$ .

- 1 Abelian Lie algebras are solvable.
- 2 Nilpotent Lie algebras are solvable, since  $L^j \subseteq L^{(j)}$ .
- 3 The subalgebra  $\mathfrak{b}_n$  of  $\mathfrak{sl}_n(K)$  consisting of all upper triangular matrices is solvable, since  $[\mathfrak{b}_n, \mathfrak{b}_n] = \mathfrak{n}_n$ .

## Proposition

Let  $L$  be a Lie algebra.

- (a) If  $L$  is solvable, then its subalgebras and homomorphic images are so.
- (b) If an ideal  $I$  of  $L$  is solvable and  $L/I$  is solvable, then  $L$  is solvable.
- (c) If  $I, J$  are solvable ideals of  $L$ , then  $I + J$  is solvable.

## Definition

Let  $L$  be a Lie algebra. The maximal solvable ideal of  $L$  is called  $\text{Rad}(L)$ , the radical ideal of  $L$ .

## Theorem

*Let  $L \subseteq \mathfrak{gl}(V)$  a solvable Lie algebra, with  $V$  a finite dimensional vector space. If  $V \neq 0$  then there exists  $v \in V$ ,  $v \neq 0$  such that  $Lv = Kv$ .*

## Theorem (Lie)

*Let  $V$  be a vector space of dimension  $n$ . If  $L \subseteq \mathfrak{gl}(V)$  is a solvable Lie algebra, then there exists a flag  $0 \subseteq V_1 \subseteq \dots \subseteq V_n = V$  such that  $xV_i \subseteq V_i$  for every  $x \in L$ ,  $i = 1, \dots, n$ .*

## Corollary

*Let  $L \subseteq \mathfrak{gl}(V)$  be a solvable Lie algebra,  $V$  a vector space of dimension  $n$ . Then there exists a basis of  $V$  such that, with respect to this basis,  $L$  is a subalgebra of the algebra  $\mathfrak{b}$  of upper triangular matrices.*

## CONCLUSION

The following are equivalent for a Lie algebra  $L$ :

- $L$  is solvable (nilpotent).
- $\text{ad}_L(L)$  is solvable (consists of nilpotent elements).
- There exists a basis of  $L$  such that  $\text{ad}_L(L)$  is contained in  $\mathfrak{b}$  (in  $\mathfrak{n}$ ).